Are the candene.com 620 in-oz motors large enough to drive a 150lb PPLLC HD Gantry?

In order to determine the force required, you need to know the weight of the gantry and the acceleration rate required for good plasma cutting.

The weight of a 6' gantry with motors and torch can be as high as 150 lbs. The acceleration rate required for good plasma cutting is 35 in/sec/sec

Force = mass x acceleration

When using English units, force has the units of pound force and mass has the units of pound mass.

Looking at the right hand side of the equation, 150 lbm x 35 in/sec/sec = 5250 lbm x in/sec/sec Since there is 12 inches per foot, we need to divide by 12 5250 / 12 = 437.5 lbm x ft/sec/sec

The relationship between pound force and pound mass is:

1 lbf = 1 lbm X gravity

Gravity is 32.174049 ft/sec/sec

Lbf = 437.5 lbm ft/sec/sec / 32.174049 ft/sec/sec

Force required (lbf) = 13.5979 lbf

This is assuming that the linear bearings are frictionless, which they are not.

Next, we need to know the force generated by the belt reduction units driving the gears on the gear rack.

Information needed:

Stepper motor torque 620 in-oz Belt reduction ratio 3.5:1 Gear pitch diameter 1" PD Gear rack pressure angle 20 degree

Since there are 16 ozf per lbf 620 / 16 = 38.75 in-lb torque motor 38.75 in-lb x 3.5 reduction = 135.625 in-lb torque reduction Since the Gear has a 1" PD, the line of force is 1/2" from the center of the shaft to the gear rack. 135.625 in-lb / .5 in = 271.25 lbf

The pressure angle between the gear and rack now needs to be factored in. Since the pressure angle is 20 degrees, the linear force is $271.25 \times 200 = 271.25 \times 200 = 271.2$

Since the gantry has 2 motors driving the 150lb gantry, the maximum force of the belt reduction units is $254.89 \text{ lbf} \times 2 = 509.78 \text{ lbf}$. Since the required torque is 13.5979 lbf, that leaves us with a safety factor of $509.78 / 13.5979 = 37.49 \times \text{what is required}$.

Even when factoring in bearing resistance and gearing / belt reduction efficiency, the motors are many times more powerful than required. That is why the stepper motors work very well in the application and do not lose steps.